



National Aeronautics and Space Administration

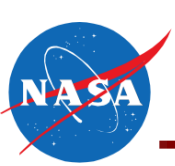
# UAS in the NAS Flight Test Series 4 Overview

**UAS Integration in the NAS Project**

**Jim Murphy: Project Engineer, Integrated Test and Evaluation**

12 May 2016





# Flight Test Series 4 Goals

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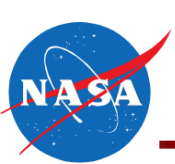
- Conduct flight tests in a relevant environment to contribute to the validation of the final Phase 1 DAA MOPS
- Develop and maintain the infrastructure for a relevant test environment for UAS research



# Flight Test Series 4 Research Objectives

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- Validate DAA requirements in stressing cases that drive MOPS requirements, including: High-speed cooperative intruder, Low-speed non-cooperative intruder, high vertical closure rate encounter, and Mode C only intruder (i.e., without ADS-B)
- Validate TCAS/DAA alerting and guidance interoperability concept in the presence of realistic sensor, tracking and navigational errors and in multiple-intruder encounters against both cooperative and non-cooperative intruders
- Validate 'Well Clear Recovery' guidance in the presence of realistic sensor, tracking and navigational errors

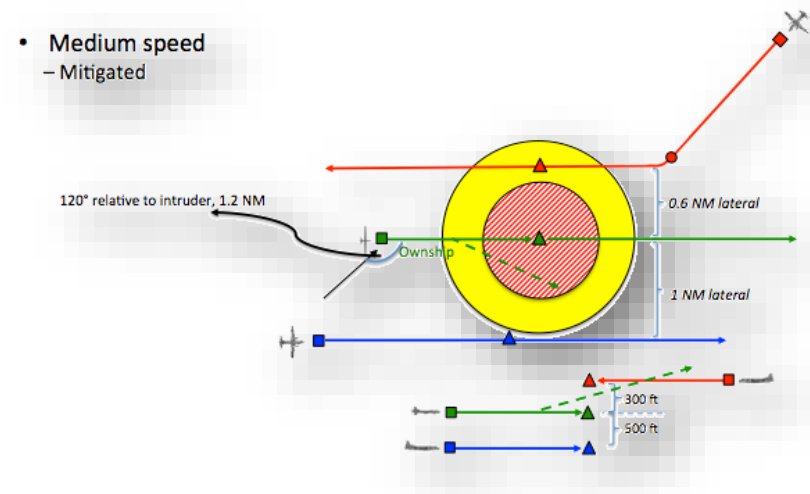


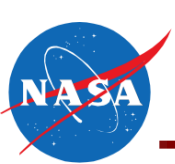
# Flight Test Series 4 Test Environment

- Support validation of final phase 1 DAA and Radar MOPS
  - Sensor noise, uncertainty
  - Navigation system errors, state data uncertainty,
  - Wind compensation
  - Support SC-228 V&V activities
- Refine DAA alerting and maneuver guidance algorithms
  - Stressing encounters
  - More complex multi-intruder encounters
  - TCAS/DAA interoperability
  - Well clear recovery
  - Mixed intruder equipage

## DAA Scripted Encounters

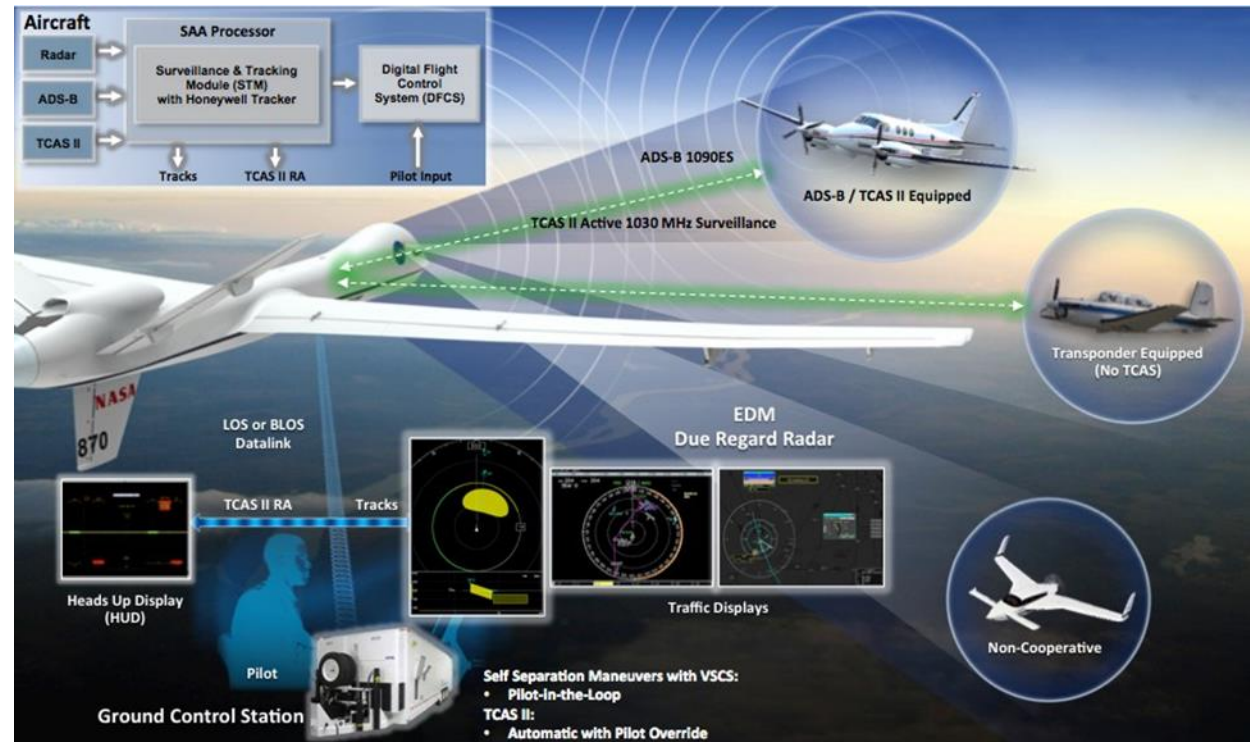
- Live Ownship with Coop and Non-Coop Sensors
- Live Intruder(s)





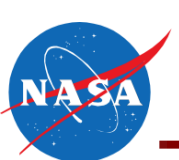
# FT4 Test System Concept

- FT4 leverages off of FT3 & ACAS Xu
- DAA Scripted Encounters only
- Data Collection for SUT:
  - JADEM
  - DAIDALUS
  - CPDS
  - TCAS
  - Radar
  - Honeywell
  - SC-228
- Sensor Evaluation
  - ADS-B
  - TCAS Hybrid Surveillance
  - EDM Radar
  - Mode C
  - Non-cooperative Target
- Flight Test Envelope Increased
  - Low Speed
  - High Speed
- Increased Intruder Requirements
  - GIII
  - TG-14
  - C-12
- Multiship Encounters 1v4
- R-2515 Test Area similar to FT3



271 encounters planned for FT4 – 20% increase from FT3

Each encounter takes approximately 10 min and planning to complete ~20 encounters per flight day



# Integration Roles & Responsibilities Summary

## NASA – AFRC (UAS-NAS / IT&E)

- Provide LVC-DE Infrastructure
- Provide Intruder Aircraft (T-34, G-III, TG-14, King Air)
- Provide Ownship Aircraft (Ikhana)
- Test Conductor Station (SAF)

NASA

Non-NASA

## NASA - ARC (UAS-NAS / IT&E)

- Provide HLA infrastructure
- RUMS Server
- Video Distribution to LaRC

## NASA - ARC (UAS-NAS / SSI)

- Provide JADEM DAA
- Provide Uncertainty model
- Devise Encounter matrix

## NASA - LaRC (UAS-NAS / SSI)

- Provide DAIDALUS DAA
- Devise Encounter matrix

## SC-228

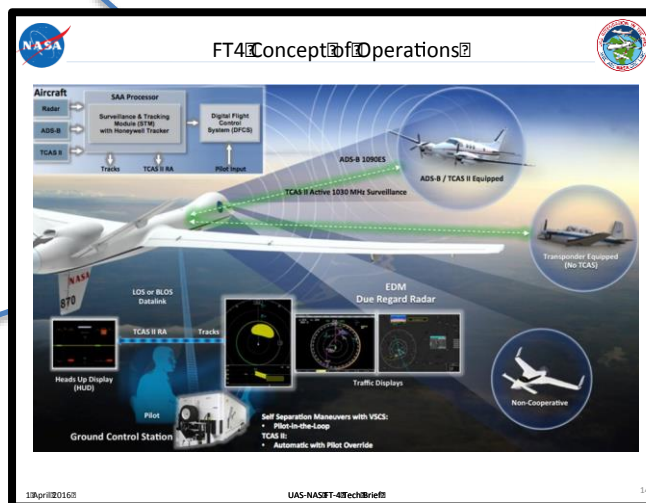
- Devise Encounter matrix

## Honeywell

- Provide instrumented TCAS II equipped intruder aircraft
- Fusion Tracker
- Post Flight Processing
- Devise Encounter matrix

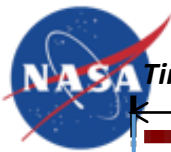
## GA-ASI

- Provide proof of concept DAA system (EDM DRR, SAAP, etc.)
- CPDS Display and IO Server
- Devise Encounter matrix



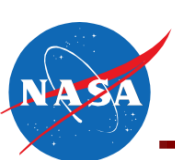


# Flight Test 4 Milestones/Key Activities



Timeline Not To Scale





# FT4 Participating Aircraft

## Aircraft Required Systems

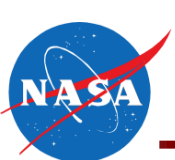
- ADS-B Out
- Mode C or S Transponder
- GPS
- DGPS w/ Recording
- VHF Comm Radio (x2)

	Aircraft	Role	EDM DRR	ADS-B	DGPS	TCAS-II	TCAS-I	Mode S	Mode C
		<b>Ownship</b> NASA AFRC Ikhana UAS	✓	✓	✓	✓		✓	✓
		<b>Primary Intruder</b> Honeywell Beechcraft King Air C90		✓	✓	✓		✓	
		<b>Secondary Intruder</b> NASA AFRC T-34		✓	✓		✓	✓	
		<b>Secondary Intruder</b> NASA AFRC King Air		✓	✓		✓	✓	
NEW		<b>High Speed / Secondary Intruder</b> NASA AFRC GIII		✓	✓	✓		✓	
NEW		<b>Low Speed / Secondary Intruder</b> NASA AFRC TG-14		✓	✓			✓	✓
NEW		<b>Secondary Intruder</b> USAF C-12 (Mode C Only)			✓				✓

Ownship – Ikhana only

New Intruders – Low Speed/RCS, High Speed, Mode C only





# Aircraft Performance

## “Low Speed” Intruder



AFRC TG-14  
(NASA 856)

### TG-14

- 100 KGS
- Small RCS (radar specific)
- Low altitude flights (5000ft-10000ft)

## “Mid Speed” Intruder



HW King Air  
(N3GC)



AFRC T-34C  
(NASA 865)



AFRC King Air  
(NASA 7 & NASA 801)

### T-34

- Up to 250 KGS
- Medium RCS (radar specific)

### King Airs

- Up to ~280 KGS
- Large RCS (radar specific)

## “High Speed” Intruder



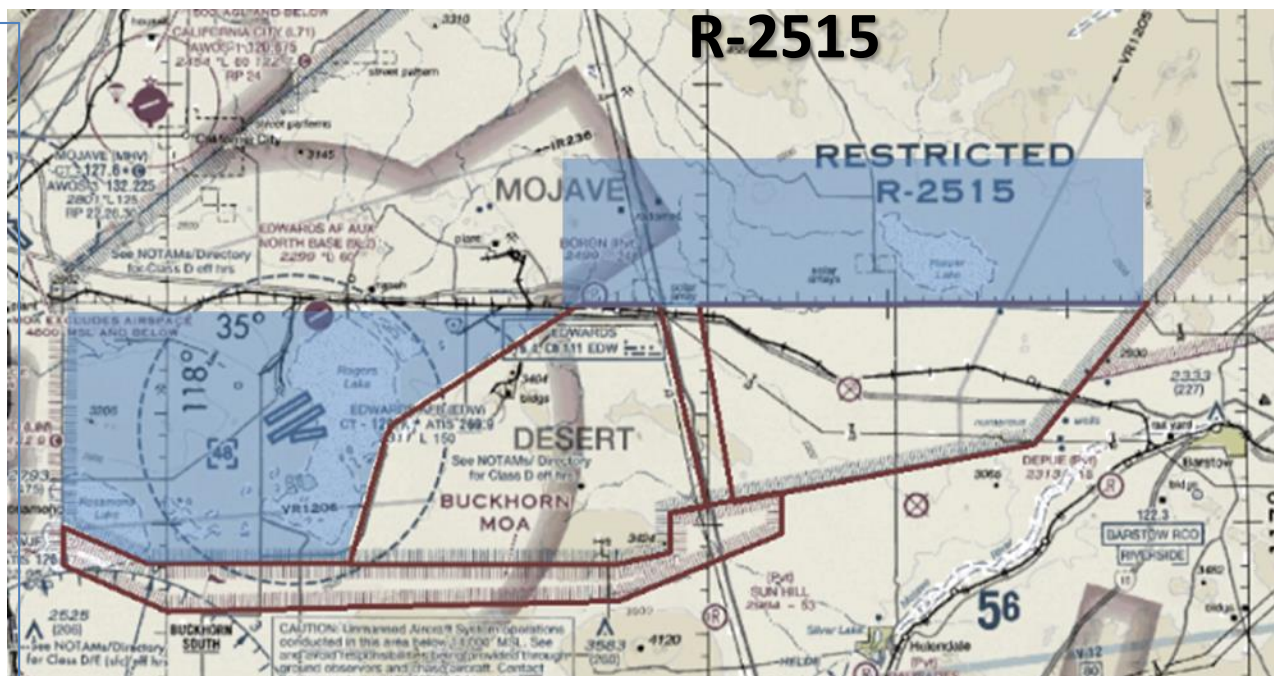
AFRC G-III  
(NASA 808)

### G-III

- Up to ~500 KTAS at 20k ft

## Airspace Planning

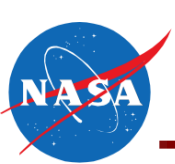
- Primarily Mercury Spin, 4 Corners & Buckhorn MOA (red outline)
- 1,000 ft AGL (4.2K ft) to 20K ft MSL
- Extensions (west / north) may be requested real time for encounters that need the additional airspace
- Ops outside of test area (blue shaded areas) are planned to be performed early (before 0800) when airspace is relatively empty
- Operations between 0600 and 0700 are under Joshua control and have less geographical constraints



### Airspace Extensions (Blue Shaded Areas)

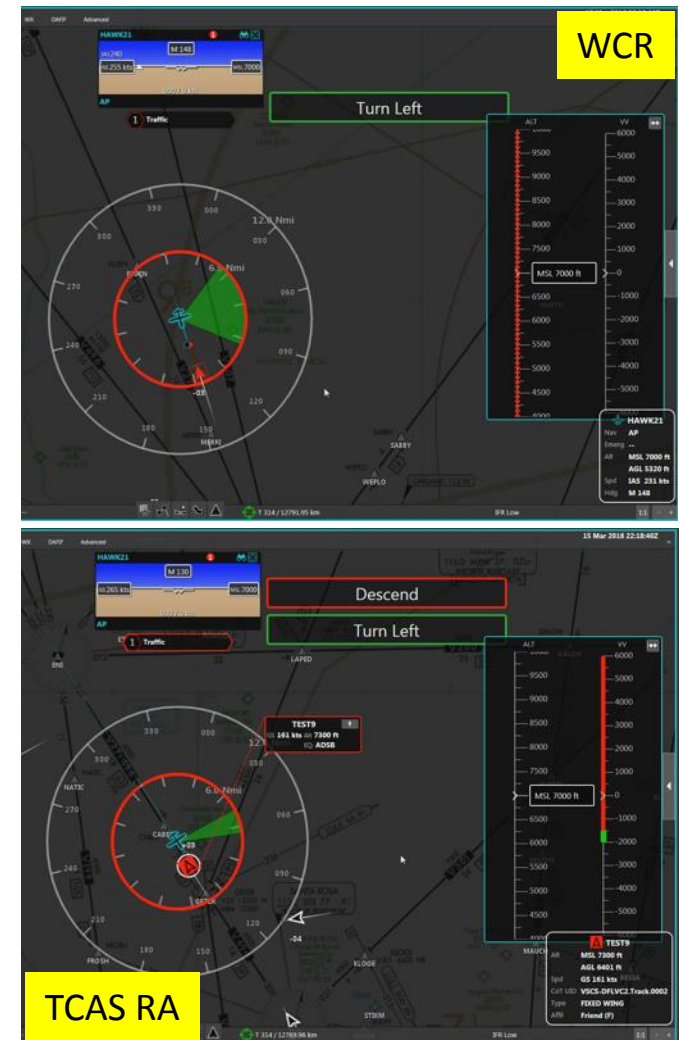
- Conducted early 0600-0800 preferably
- Pre-coordinated 24-48 hours in advance
- Requested real-time with SPORT (after 0700)

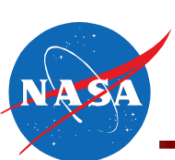
**Ikhana must remain within R-2515 at all times. Intruder aircraft can use Buckhorn MOA, plus areas shaded in blue.**



# FT4: NASA DAA Suite: JADEM/VSCS

- Java Architecture for DAA Extensibility and Modeling (JADEM) software:
  - Subscribes to LVC GW for ownship and intruder flight state data (flight state message).
  - Subscribes to LVC GW for TCAS RA messages.
  - Contains DAA algorithm for conflict detection and resolution.
  - Contains DAA/TCAS interoperability logic.
  - Publishes DAA conflict resolution as heading bands and altitude tape keep out zones.
  - Publishes Well Clear Recovery (WCR) as suggestive guidance.
- Vigilant Spirit Control Station (VSCS) software:
  - Developed by AFRL as an integrated ground control station for command and control of UAS.
  - VSCS Tactical Situation Display (TSD) augmented by AFRL with DAA display elements to support NASA Human Systems Integration (HSI) objectives.
  - VSCS TSD serves as the Cockpit Display for Traffic Information (CDTI) for SSI-West experiment.
  - VSCS TSD displays DAA and WCR guidance produced by JADEM.
  - VSCS TSD displays TCAS RA aural and visual alerts.





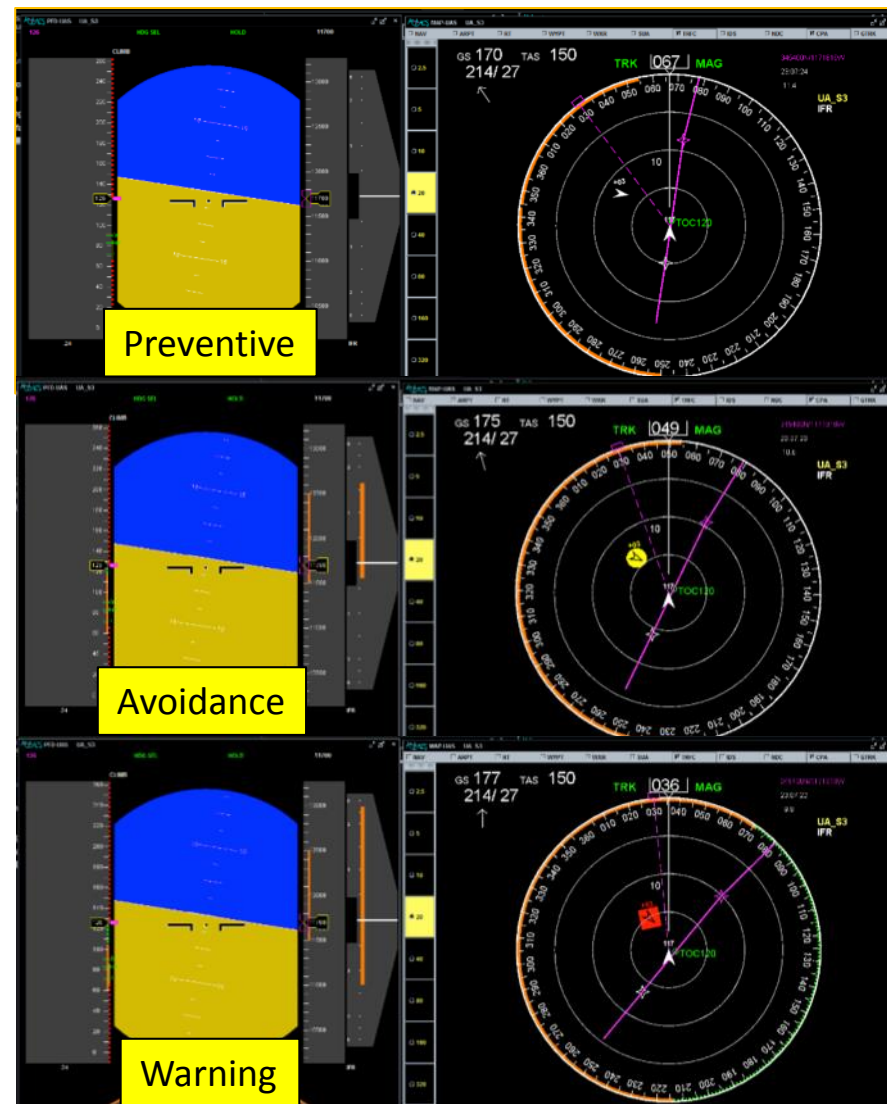
## FT4: NASA DAA Suite: DAIDALUS/MACS

### • DAIDALUS:

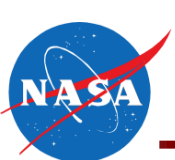
- Subscribes to LVC GW for ownship and intruder flight state data (flight state message).
- Subscribes to LVC GW for TCAS RA messages.
- Contains DAA algorithm for conflict detection and resolution.
- Contains DAA/TCAS interoperability logic.
- Provides DAA avoidance and recovery bands.
- Provides WCR band.

### • MACS:

- Adapted for use as a DAA test bed.
- Displays DAA guidance from DAIDALUS on generic HSI, VSI, and altitude instruments.
- VSI DAA bands replaced by TCAS guidance during RAs.
- Displays WCR band.



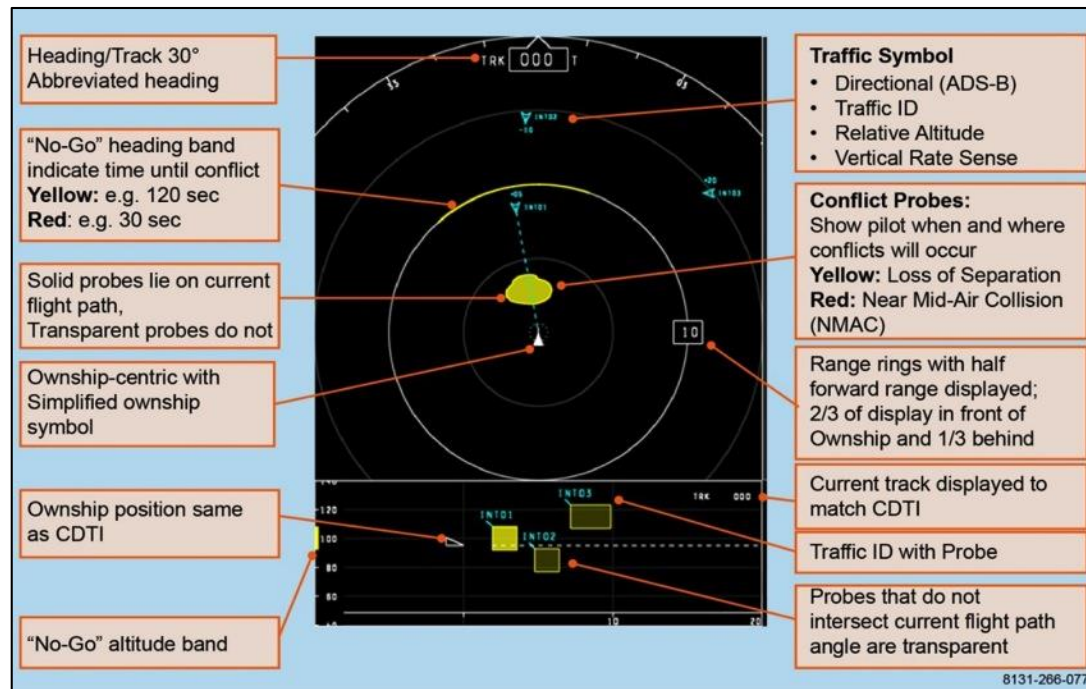


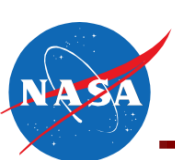


# FT4: GA-ASI CPDS

## • CPDS:

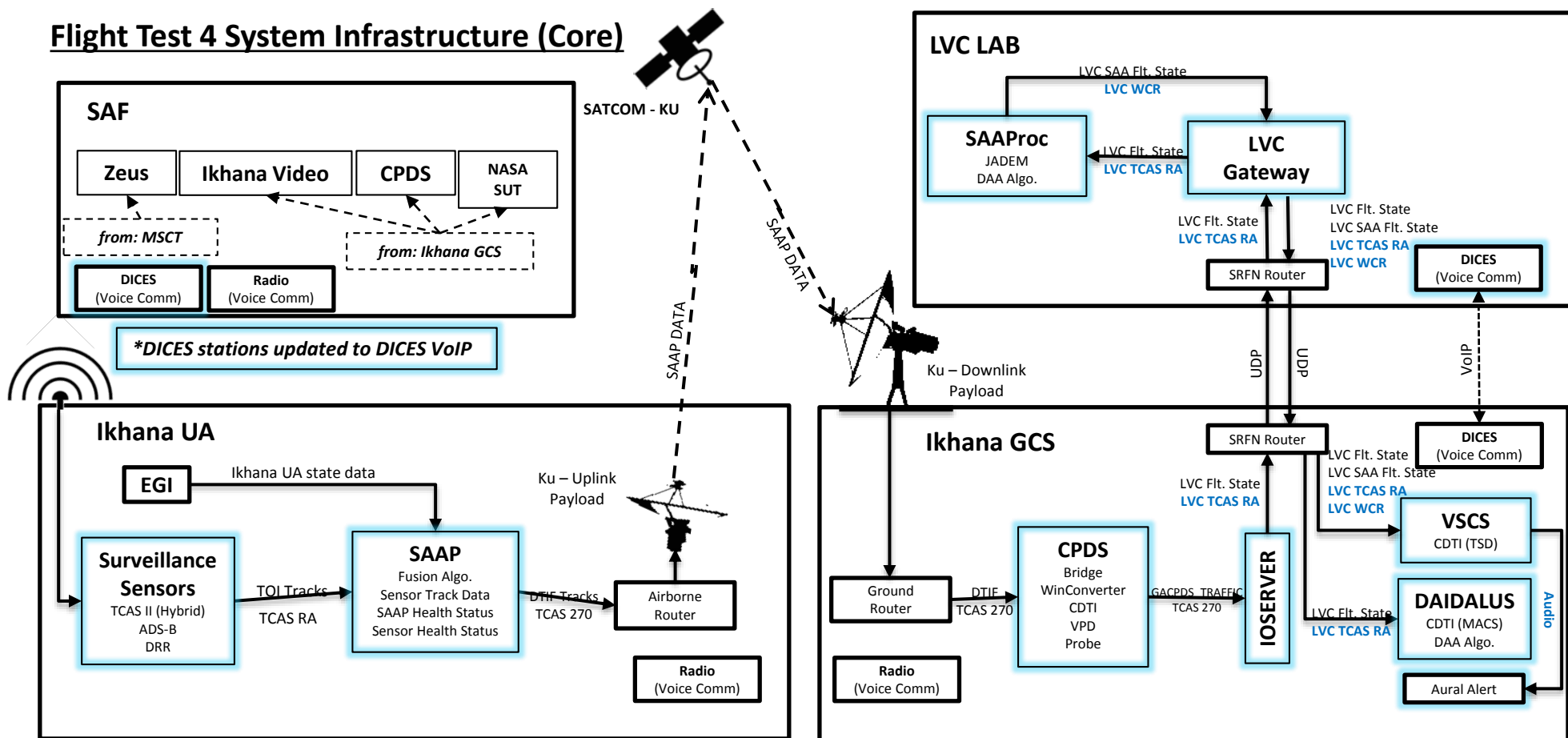
- Receives ownship and surveillance tracks from the SAAP.
- Displays Ownship and Surveillance track data on the CDTI display and VPD.
- Processes surveillance tracks through its DAA algorithm to create conflict probes displayed on CDTI and VPD.
- Provides engineering display (Winconverter) with additional data on ownship and intruder.
- Bridge module provides option to select adding UTC offset to the received A735B with readout to verify offset.
- Bridge module includes fractional seconds in the time put in to the GA\_CPDS traffic topic. Allowing IOserver to forward time.
- Winconverter proxy panel to suppress certain data to CPDS domain.
- Winconverter capability to send DAA alerts to HUD (if connected to flight network).
- CDTI added North-up option.





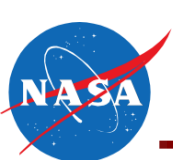
# FT4: Core System Infrastructure

## Flight Test 4 System Infrastructure (Core)

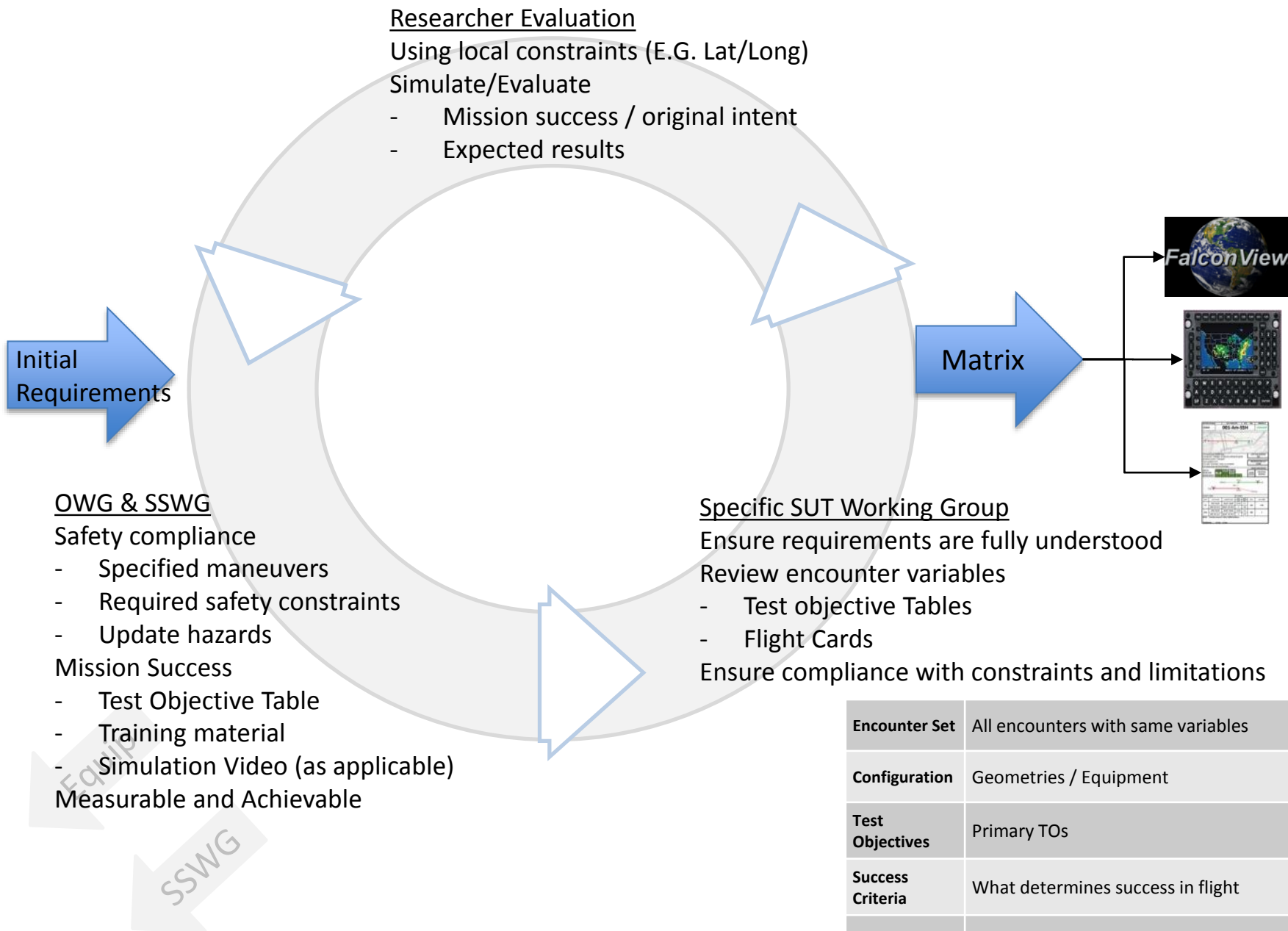
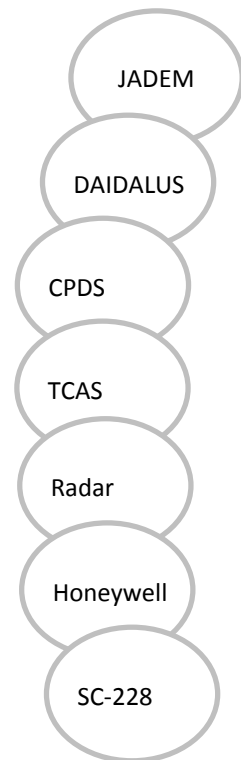


FT4 leverages off a core system infrastructure used for ACAS-Xu and FT3 test missions. Major changes to FT4 occur at the software level.

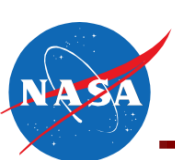




# Encounter Planning Process



Encounter Set	All encounters with same variables
Configuration	Geometries / Equipment
Test Objectives	Primary TOs
Success Criteria	What determines success in flight
Test Methods	Procedures to achieve success criteria
Evaluation Criteria	Post flight analysis / data collection



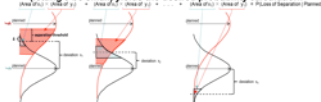
# Encounter Tolerance Development

## ACAS Xu

- Probabilistic approach 99.7%
- Min offsets:
  - 200' vertical
  - 0.5 nmi lateral
  - $\pm 5, 8, 10$  sec
- Altimeter & navigation calibration
- Mission Rules

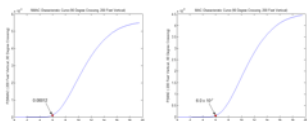


Assuming a separation threshold, an integration over PDFs (letting  $\delta$  be small) yields the desired probability calculation:



### Results:

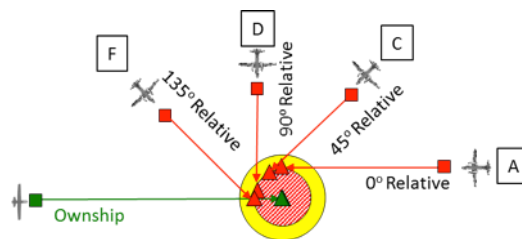
- Probability( $<100$  Feet Separation | 200 Feet Planned) = 0.0089
- Probability( $<20$  Feet Separation | 200 Feet Planned) = 0.0032
- Probability( $<100$  Feet Separation | 300 Feet Planned) = 0.0016
- Probability( $<20$  Feet Separation | 300 Feet Planned) = 1.5e-05
- Probability( $<100$  Feet Separation | 500 Feet Planned) = 1.3e-09
- Probability( $<20$  Feet Separation | 500 Feet Planned) = 4.4e-13



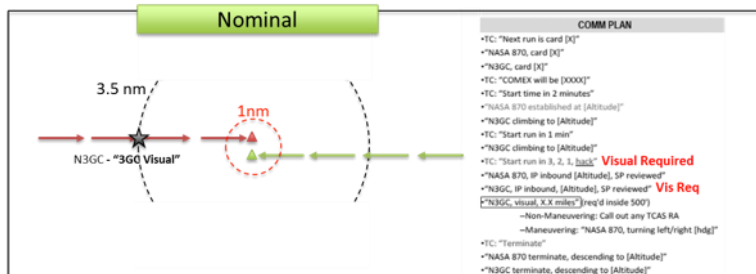
- Planned (known) Vertical Separation:
  - 5000 and 2000
- Normal Distribution based on Standard Deviation
  - AC 91-85 (RVSM) defines altitude keeping SD
  - Standard Deviation of 40ft
  - Flight test calibration logs consider errors between aircraft
  - Allows for up to 25 feet altitude difference (each within 12.5 feet of "true")
  - These standard deviations contain 99.7% of the probability
  - We can safely assume 10 feet SD for instrument error
- GA Autopilot Altitude Mode standard deviation
  - Request for information
- Current Assumptions on SD to perform analysis
  - 60 Feet SD for manned aircraft
  - 30 Feet SD for unmanned aircraft

## FT3

- Deterministic approach
  - Leveraged off of ACAS Xu
- Min offsets:
  - 200' vertical
  - 0.5 nmi lateral
  - $\pm 5, 8, 10$  sec
- Altimeter calibration
- Mission Rules

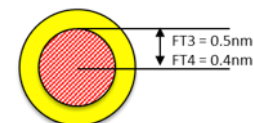
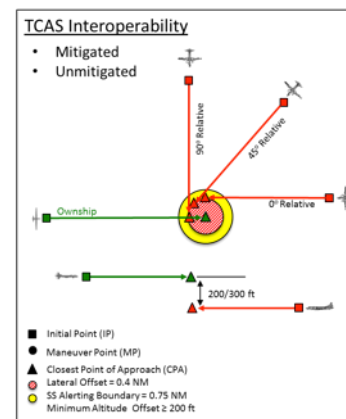


- Initial Point (IP)
- Maneuver Point (MP)
- ▲ Closest Point of Approach (CPA)
- Lateral Offset = 0.5 nmi
- SS Alerting Boundary = 0.75 nmi
- Minimum Altitude Offset  $\geq 200$  ft
- Priority



## FT4

- Deterministic approach
  - Leveraged off of FT3
- Min offsets:
  - 200' vertical
  - **0.4 nmi lateral**
  - $\pm 5, 8, 10$  sec (**DAA Real Time**)
- Altimeter calibration
- Mission Rules



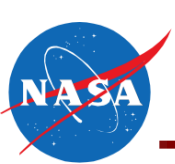
Decreased to 0.4 nm horizontal separation. Required to achieve TCAS alerting below 10K

## ACAS – FT3

- High Confidence with ACAS-Xu offsets
- Mission Success criteria closely approximated ACAS-Xu
- Nav/Cal- not measureable, no added value or increase safety margins

## FT3 – FT4

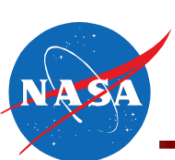
- High Confidence with previous test planning criteria
- Decrease from 0.5 to 0.4 nm horizontal offset for mission success and;
- Engineering & crew judgment – min acceptable levels of safety are maintained



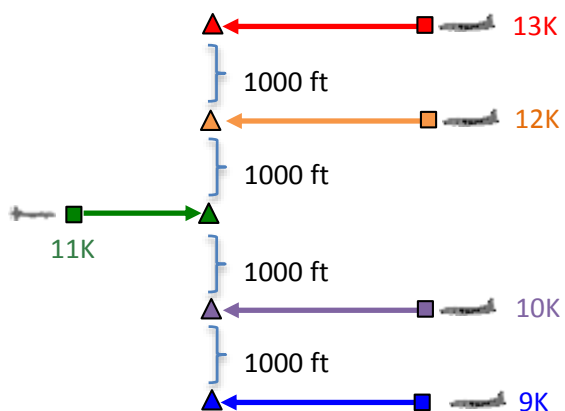
# Ikhana FT-4 Mission Flights

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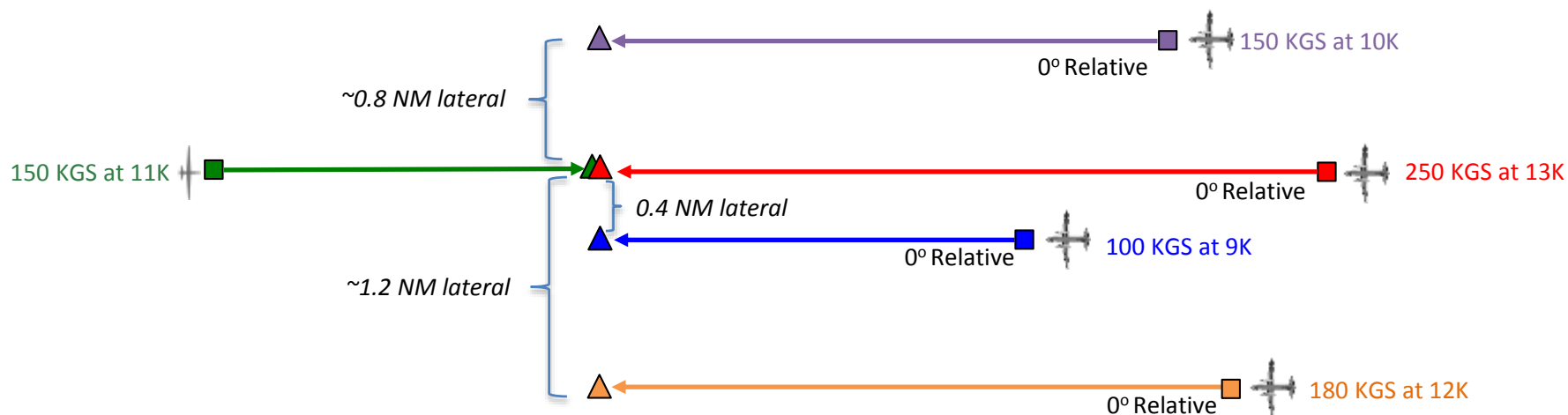
- 15 Flights Planned
  - Tuesdays and Thursdays, late April through June
- Up to 6.5 hour flights planned
- Single and Multiple Intruders
  - 1, 2, or 4 manned aircraft
    - Honeywell, NASA AFRC, and/or AF aircraft
- Objectives
  - Using various geometries, closing airspeeds, and altitudes
    - Demonstrate FT-4 system performance
      - Within approved FT-4 test envelope
    - Demonstrate various Self-Separation display systems
      - GA-ASI: Conflict Prediction and Display System (CPDS)
      - NASA: JADEM and DAIDALUS



# Multiship (7) Four Intruders



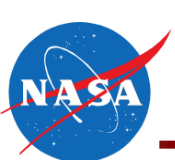
- Mixed speeds
  - Unmitigated



- Initial Point (IP)
- Maneuver Point (MP)
- ▲ Closest Point of Approach (CPA)

New for FT4

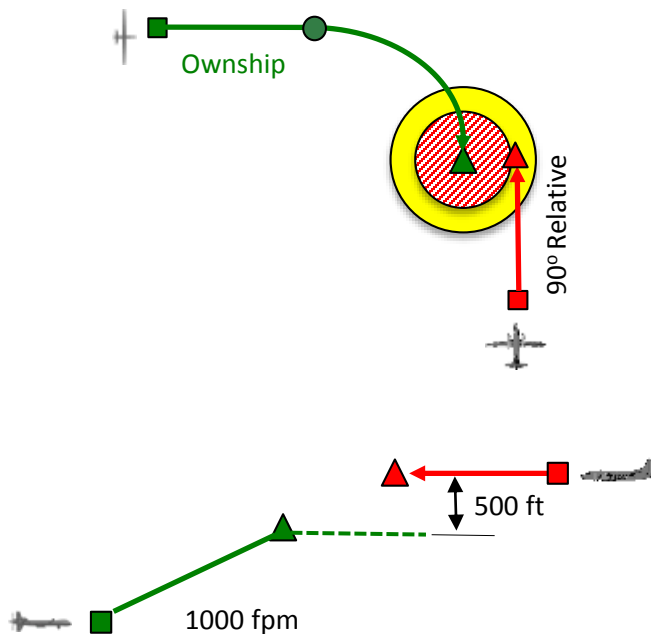
- 4 intruders, but simple fly-through encounter



# Medium Speed Intruder (4)

## Ownship Maneuver and Climb

- Mitigated

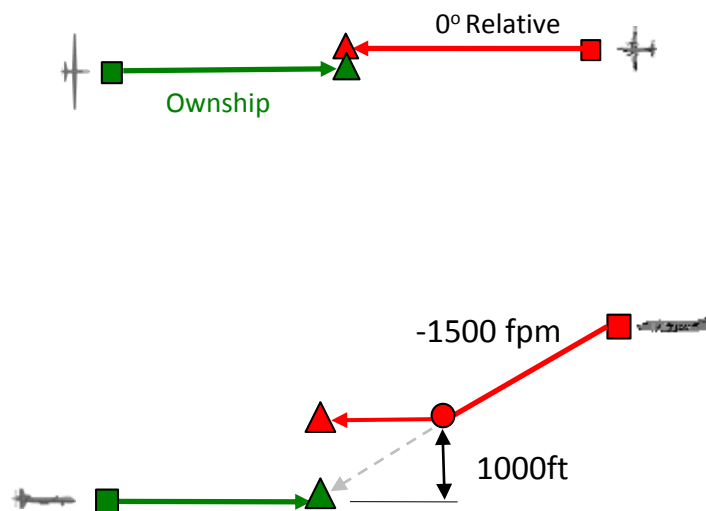


- Initial Point (IP)
- Maneuver Point (MP)
- ▲ Closest Point of Approach (CPA)
- ⊗ Lateral Offset = 0.4 NM
- SS Alerting Boundary
- Minimum Altitude

New for FT4  
-Ikhana turning and climbing

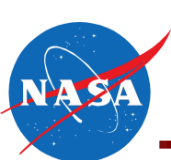
## Intruder Blunder and Level Off

- Unmitigated



- Initial Point (IP)
- Maneuver Point (MP)
- ▲ Closest Point of Approach (CPA)

Same encounter variables as FT3

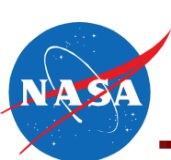


# Single Intruder Test Card

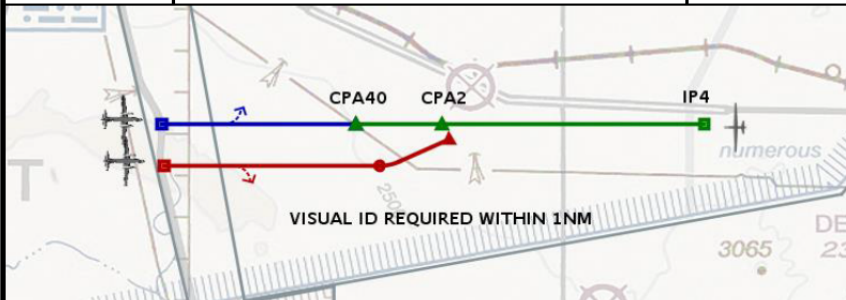
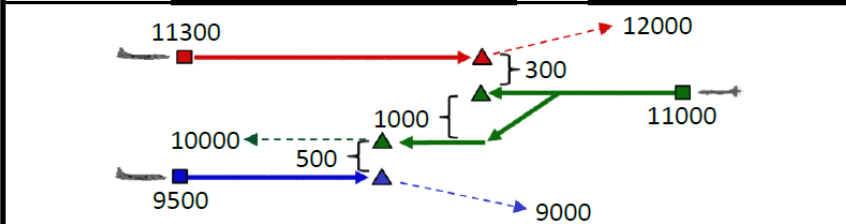
FT4 DAA Scripted	A/C: NASA 870	S/N: 001	VERSION 4			
CARD#	<b>001-Am-S5H</b>	OWNSHIP				
1. TC announces COMEX time. 2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP. 3. On condition at IP. 4. TC calls "terminate" when run complete. 5. TC announces next Card Number.		LOST LINK MISSION: TBD  DECONFLICTION ALT: 15500				
DISPLAY: MANEUVER: SENSOR SELECT:		ABORT PROCEDURE				
JADEM DAIDA. CPDS OFF Advisory AUTO Tracker Radar ADS-B TCAS		15500 MAINTAIN HEADING				
COMEX TIME:		IP WIND:				
WPT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	KGS	LEG TIME
IP1	N34° 55.20'	W117° 14.89'	15500	6.7	200	2+00
	N34° 55' 11.7"	W117° 14' 53.5"	0	258		
CPA2	N34° 55.20'	W117° 23.02'	15500	0.0	200	0
	N34° 55' 11.7"	W117° 23' 01.3"	0	258		
NOTES: Ownship maneuver. Follow JADEM Guidance.						
TOLERANCE: ± 8 sec ± 5 kts						

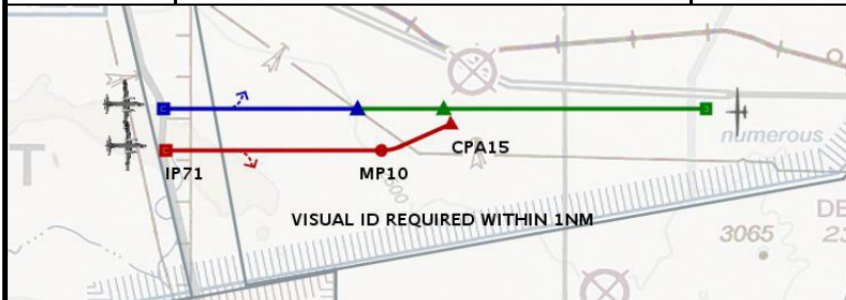
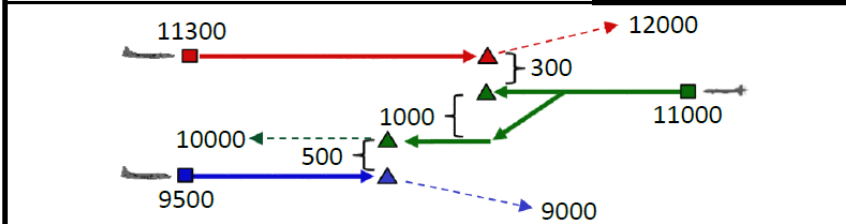
FT4 DAA Scripted	A/C: NASA 808	S/N: 001	VERSION 4			
CARD#	<b>001-Am-S5H</b>	INTRUDER 1				
1. TC announces COMEX time. 2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP. 3. On condition at IP. 4. TC calls "terminate" when run complete. 5. TC announces next Card Number.		DECONFLICTION ALT: 14500				
DISPLAY: MANEUVER: SENSOR SELECT:		ABORT PROCEDURE				
JADEM DAIDA. CPDS OFF Advisory AUTO Tracker Radar ADS-B TCAS		14500 123				
COMEX TIME:		IP WIND:				
WPT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	KGS	LEG TIME
IP52	N34° 55.20'	W117° 40.10'	15000	14.0	420	2+00
	N34° 55' 11.7"	W117° 40' 05.8"	0	078		
CPA2	N34° 55.20'	W117° 23.02'	15000	0.0	420	0
	N34° 55' 11.7"	W117° 23' 01.3"	0	078		
NOTES: Expect Ownship maneuver.						
TOLERANCE: ± 8 sec ± 5 kts						

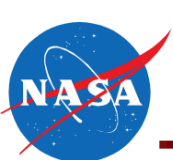




# Multiship Intruder Test Card (1)

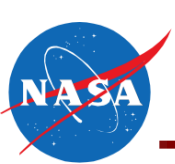
FT4 DAA Scripted	AIRCRAFT: NASA 870	S/N: 47	VERSION 4			
CARD#	<b>047-Am-M3M</b>	OWNSHIP				
						
1. TC announces COMEX time.		LOST LINK MISSION: TBD				
2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP.						
3. On condition at IP.		DECONFLICTION ALT: 11000				
4. TC calls "terminate" when run complete.						
5. TC announces next Card Number.						
ABORT PROCEDURE						
DISPLAY:	JADEM	DAIDA	CPDS			
MANEUVER:	OFF	Advisory	AUTO			
SENSOR SELECT:	Tracker	Radar	ADS-B TCAS			
						
COMEX TIME:		IP WIND:				
WPT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	KGS	LEG TIME
IP4	N34° 55.20'	W117° 15.71'	11000	6.0	180	2+42
	N34° 55' 11.7"	W117° 15' 42.3"	-1000	258		
CPA2	N34° 55.20'	W117° 23.02'	10000	0.0	180	0
	N34° 55' 11.7"	W117° 23' 01.3"	0	258		
CPA40	W34° 55.20'	W117° 25.44'	10000	0	180	0
	N34° 55' 11.7"	W117° 25' 26.2"	0	258		
NOTES: Ownship maneuver. Follow TCAS RA Guidance for Intruder 1. Follow JADEM Guidance for Intruder 2.						
TOLERANCE: ± 8 sec ± 5 kts						

FT4 DAA Scripted	A/C: N3GC	S/N: 47	VERSION 4			
CARD#	<b>047-Am-M3M</b>	INTRUDER 1				
						
1. TC announces COMEX time.		DECONFLICTION ALT: 12000				
2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP.						
3. On condition at IP.						
4. TC calls "terminate" when run complete.						
5. TC announces next Card Number.						
ABORT PROCEDURE						
		12000	123			
						
COMEX TIME:		IP WIND:				
WPT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	KGS	LEG TIME
IP71	N34° 54.20'	W117° 30.78'	11300	6.7	200	2+42
	N34° 54' 11.7"	W117° 30' 46.9"	0	078		
MP10	N° 34' 54.2"	N1° 17' 24.8"	11300	0.5	200	0
	N34° 54' 11.7"	N117° 24' 46.2"	0	066		
CPA15	N34° 54.83'	W117° 22.82'	11300	0.0	200	0
	N34° 54' 50.0"	W117° 22' 49.0"	0	053		
NOTES: Expect Ownship maneuver.						
TOLERANCE: ± 8 sec ± 5 kts						



# Multiship Intruder Test Card (2)

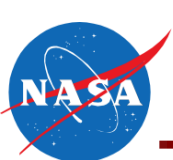
FT4 DAA Scripted		A/C: NASA 856		S/N: 47		VERSION 4	
CARD#		<b>047-Am-M3M</b>				INTRUDER 2	
1. TC announces COMEX time. 2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP. 3. On condition at IP. 4. TC calls "terminate" when run complete. 5. TC announces next Card Number.							
						DECONFLICTION ALT: <b>10000</b>	
						ABORT PROCEDURE	
						<div style="border: 1px solid black; padding: 5px; display: inline-block;">9000</div> <div style="display: inline-block; vertical-align: middle;">  033       </div>	
COMEX TIME:				IP WIND:			
WPT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	KGS	LEG TIME	
IP134	N34° 55.20'	W117° 30.84'	9500	4.4	100	2+42	
	N34° 55' 11.7"	W117° 30' 50.6"	0	078			
CPA40	N34° 55.20'	W117° 25.44'	9500	0.0	100	0	
	N34° 55' 11.7"	W117° 25' 26.2"	0	078			
NOTES: Expect Ownship maneuver.							
TOLERANCE: ± 8 sec ± 5 kts							



# Minimum Separation

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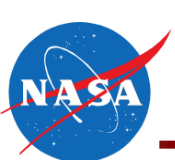
- The minimum geospatial offsets planned are 200 feet vertical and 0 foot horizontal (although not simultaneously during any test run)
- Test encounters with a minimum vertical separation of less than 500 feet will include a lateral offset of at least 2430 feet (0.4 nmi)
  - Allows for some built-in safety margin that still meets well-clear volume requirements and test data collection objectives
- Test encounters more than or equal to 500 feet vertical offset may have a 0 foot horizontal offset.
- All participating aircraft will ensure the aircraft altimeter system meets manufacturer calibration specifications and requirements for normal operation in the NAS.
- A maximum of 608 feet (0.1 nmi) navigation error (GPS derived position) is allowed for each aircraft based on the system's built-in navigation accuracy readout.



# Ikhana FT-4 Nominal Encounter Mission Flow

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- T-1: Day before detailed brief
  - Protect crew rest for back-to-back flights possible if back up dates are utilized
- T-0 All: All crew pre-flight delta brief
- T-0 Ikhana: Individual aircraft crew brief, as required
- Each aircraft take-off to arrive within R2515 at required time
  - 0600 ish for Ikhana
- Ikhana and manned aircraft perform altitude calibration, as required
- Prior to each encounter verify encounter, configuration, visual ID requirement, expected behavior, and abort procedures per UAS-NAS encounter cards and Ikhana flight cards



# Ikhana FT-4 Nominal Encounter Mission Flow (cont)

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- Execute Encounter
- Between Encounters
  - Maneuver Mode: Advisory/Off
  - Maintain previous encounter deconfliction altitude until laterally separated and as directed by TD for upcoming encounter
  - Configure for next encounter set up
- Execute additional encounters per flight cards
- RTB, as appropriate
- Land
- De-brief

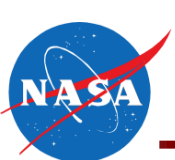


# FT4 Mission Management Responsibilities

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- **Test Conductor**
  - Manages mission execution over voice communication on mission net (VHF radio) with Ikhana pilot, intruder pilots, and SPORT
- **Test Director**
  - Primary liaison with test conductor
  - Manages voice communication on test team net with Ikhana mission director, SOR, LVC, local agencies, and non-local agencies (as required)
- **Mission Directors**
  - Communicates directly with co-located pilots within GCS, test director, and other agencies (as required)
- **LVC**
  - Communicates with test director on test team net to provide real-time discussions on live virtual constructive performance (as required)
- **Senior Operations Representative (SOR)**
  - Independent representative of the Code O director with authority to stop a test if it is deemed that the test team is making unauthorized changes to the briefed test cards, is confronted with unanticipated events that should be addressed on the ground, or other issues that might arise that warrant a test to be stopped and reevaluated in a less dynamic environment than in the middle of a test mission
- **Range Control Officer**
  - RCO monitors and makes coordination calls with Armstrong COMM and the SAF DATR mission system ops folks (as required)





# FT4 Mission Support Software

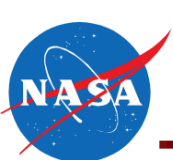


## Zeus

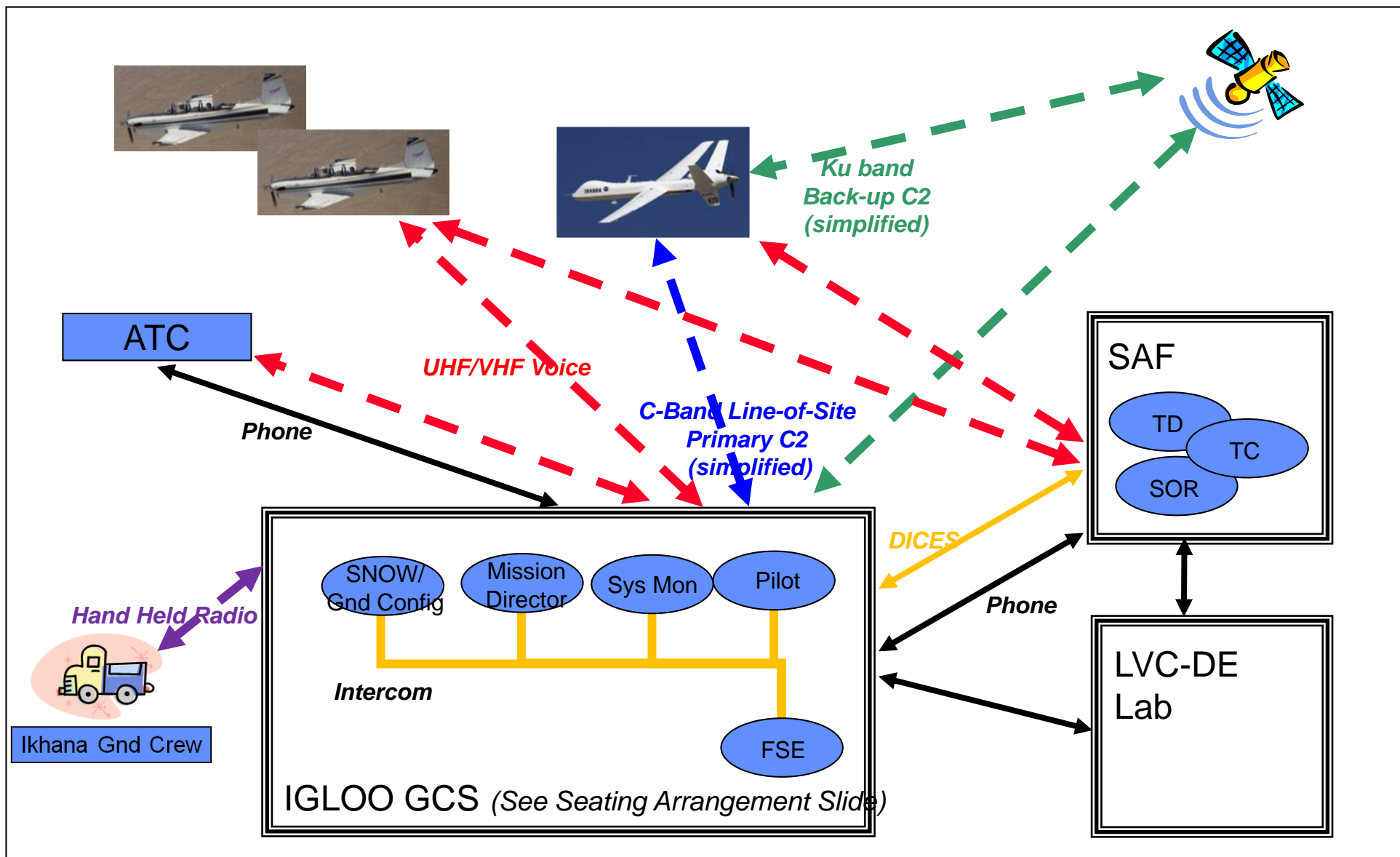
- Thales ADS-B receiver integrated

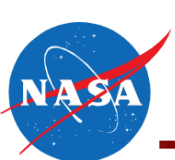
## Quicklook 2

- MITLL product in development
- Operates using a stand alone computer
- May be installed prior to FT4
- Will not be used as a SA display for FT4

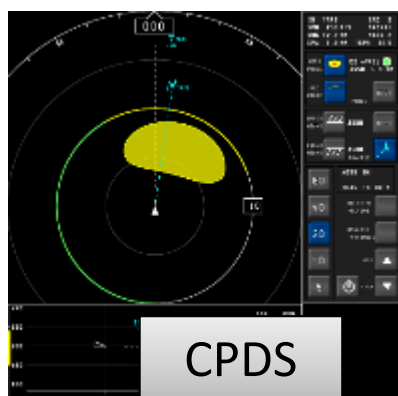
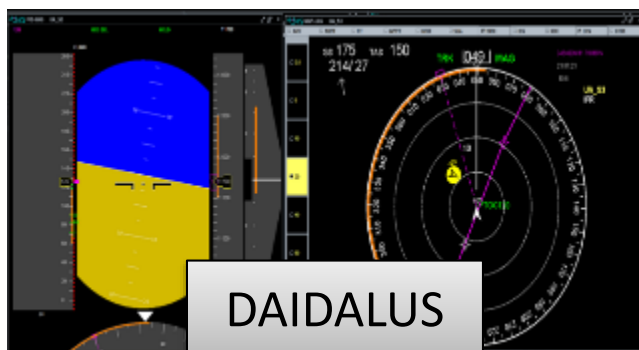
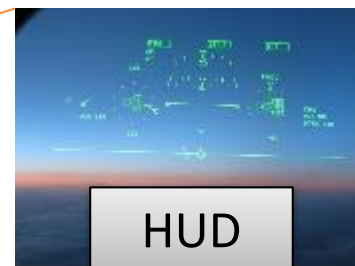


# Ikhana UAS Communication – FT-4 Flights





# FT4 Displays Under Test



- DAA Display's are located to the left of PPO-1 Station
- HUD will display TCAS alerting. HDD's display TCAS WCA
- When specifically configured HUD will display DAA and TCAS alerting (Only 1 flight)
- Aural Alerts (Commands and Tone)
  - GCS will annunciate a TCAS alert tone
  - JADEM SUT will annunciate a TCAS alert commands



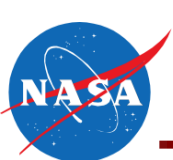
SUT

Aural Alerts



GCS

Aural Alerts

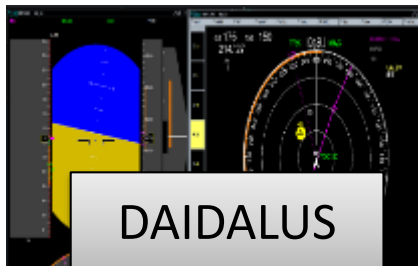


# FT4 Displays Under Test

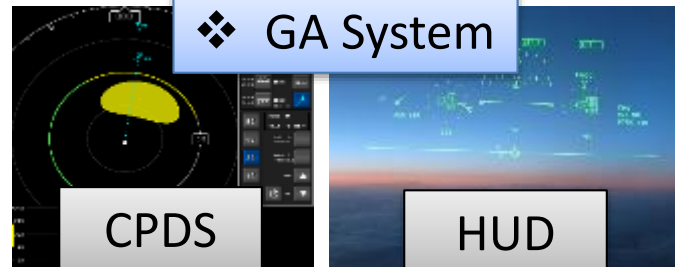
(Pilot/User centric)



JADEM



DAIDALUS



GA System

CPDS

HUD

DAA Alerts (VSCS)



Heading Bands  
"Turn Heading ###"

DAA Alerts (VSCS / DAIDALUS Display)



Heading Bands

FT3 Capabilities

DAA Alerts



Lateral & Vertical

TCAS Alerting



Vertical



DAA Alerting (VSCS)



Heading Bands

DAA Alerting (DAIDALUS Display)



Heading Bands

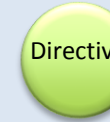
FT4 Similarities

DAA Alerts



Lateral & Vertical

TCAS Alerting



Vertical



DAA Alerting



Vertical Bands  
WCR

TCAS Alerting



Vertical Commands



DAA Alerting



Vertical Bands

TCAS Alerting



Vertical Commands



FT4 Differences

DAA Alerts



Lateral & Vertical

TCAS Alerting

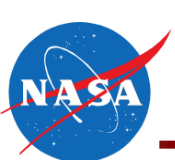


Vertical

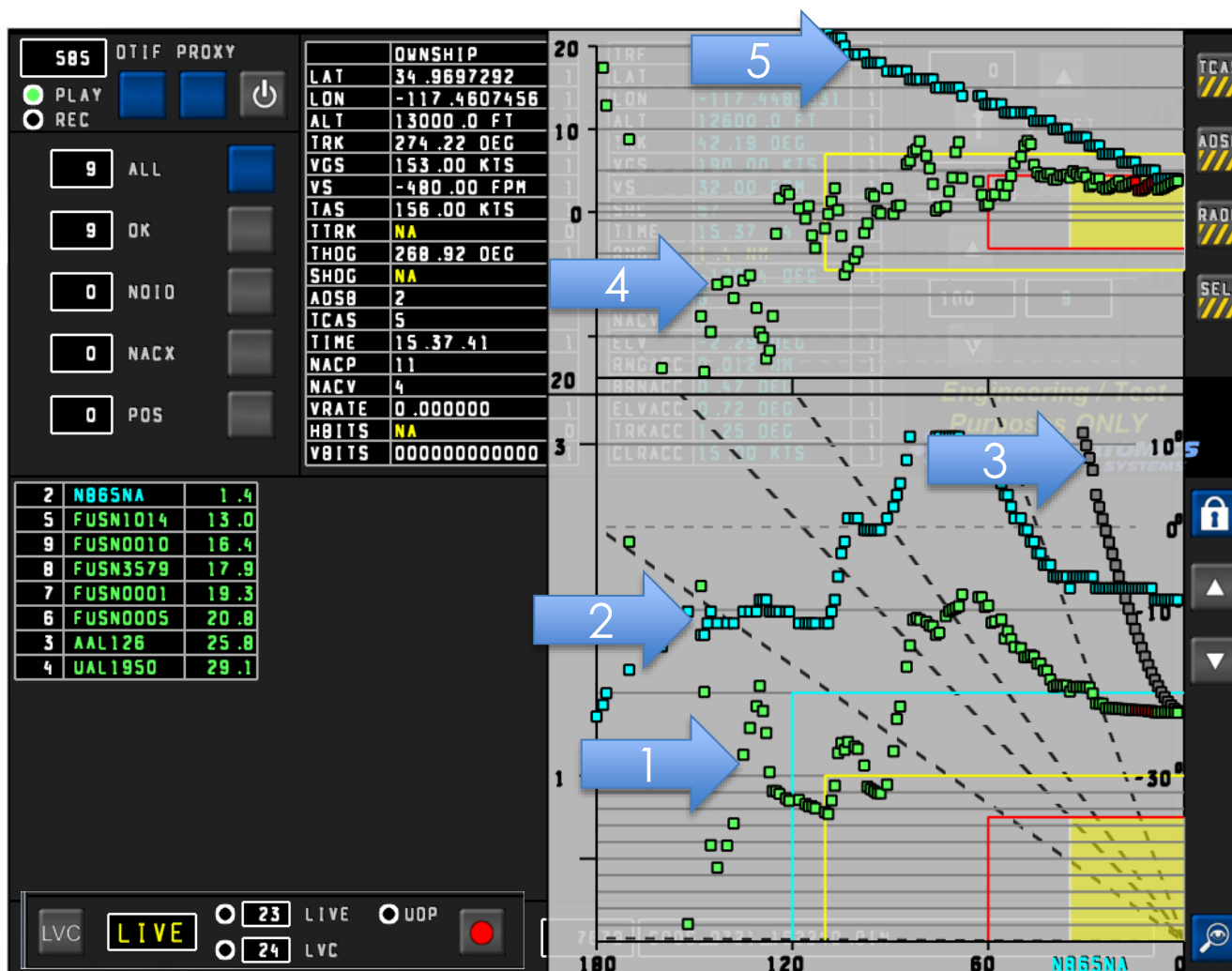
TCAS Alerting  
Additional commands available



DAA alerts displayed on HUD  
for 1 flight.



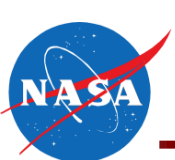
# Winconverter with DCPA\* plot enabled



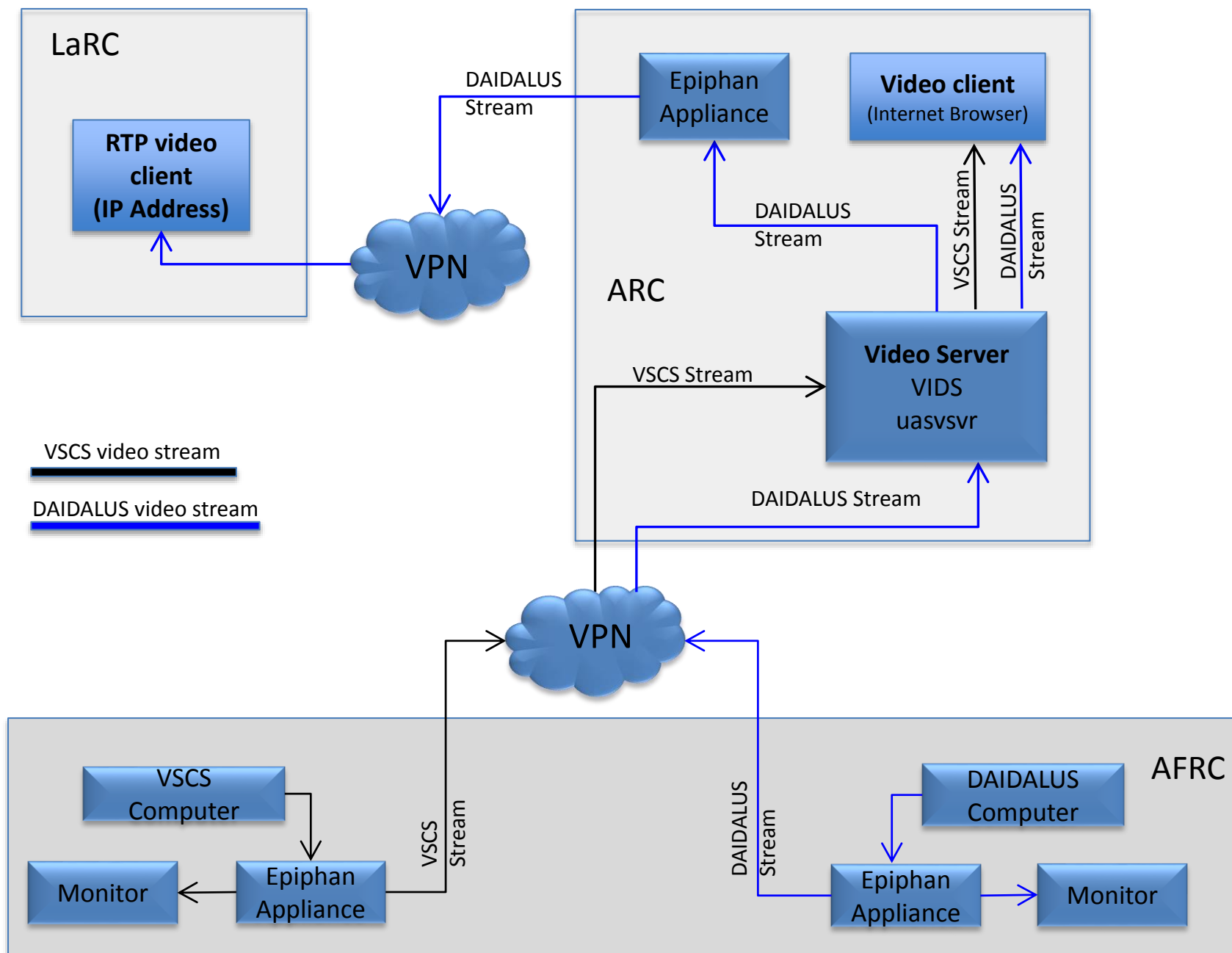
\*DCPA: Distance at Closest Point of Approach

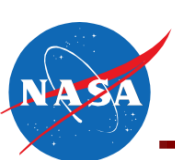




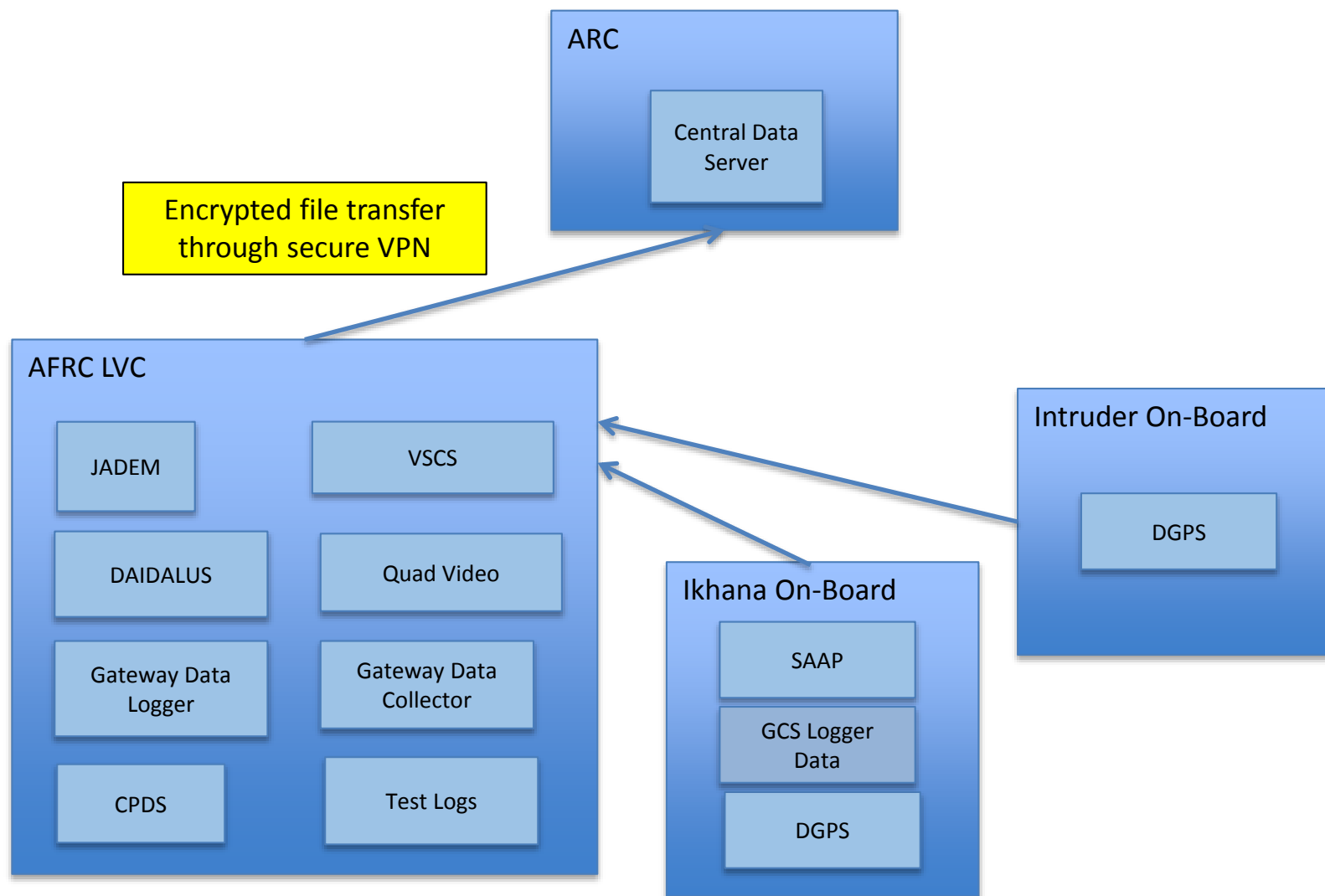


# Configuration: Video Streaming





# Data Collection Archiving



Reference: Flight Test Series 4 Data Management Plan, FT4 IT&E DMP-001



# Flight Test 4 Flight Schedule

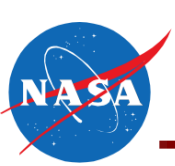


- Seeking approval from Tech Brief Board to fly FT4 Flight Test Series using current available integrated and tested version of LaRC provided DAIDALUS software.

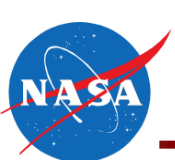
	FT4 Plan A (Baseline Version of DAIDALUS only)																									
	April								May								June									
	4 - 8		11 - 15		18 - 22		25 - 29		2 - 6		9 - 13		16 - 20		23 - 27		30 - 3		6 - 10		13 - 17		20 - 24		27 - 1	
Sys Check Flts																										
Env																										
Exp/Training																										
JADEM Flts																										
Radar Flts																										
CPDS Flts																										
TCAS Flts																										
HW Flts																										
SC-228 Flts																										
DAIDALUS Flts																		No Fly (3-day wk)								

- LaRC working to update DAIDALUS software (final version) to be able to flight test with final version.
- Project approach:
  - Software needs to be delivered by 5/23 in order to meet FT4 completion milestone (L1) of 6/30/16.
  - 2-3 weeks of regression testing
  - Mini-tech updates
  - Complete DAIDALUS flights at the end of June

	FT4 Plan B (Final Version of DAIDALUS available by May 23)																											
	April								May										June									
	4 - 8		11 - 15		18 - 22		25 - 29		2 - 6		9 - 13		16 - 20		23 - 27		30 - 3		6 - 10		13 - 17		20 - 24		27 - 1			
Sys CheckFlts																												
Env																												
Exp/Training																												
JADEM Flts																												
Radar Flts																												
CPDS Flts																												
TCAS Flts																												
HW Flts																												
SC-228 Flts																												
																											35	

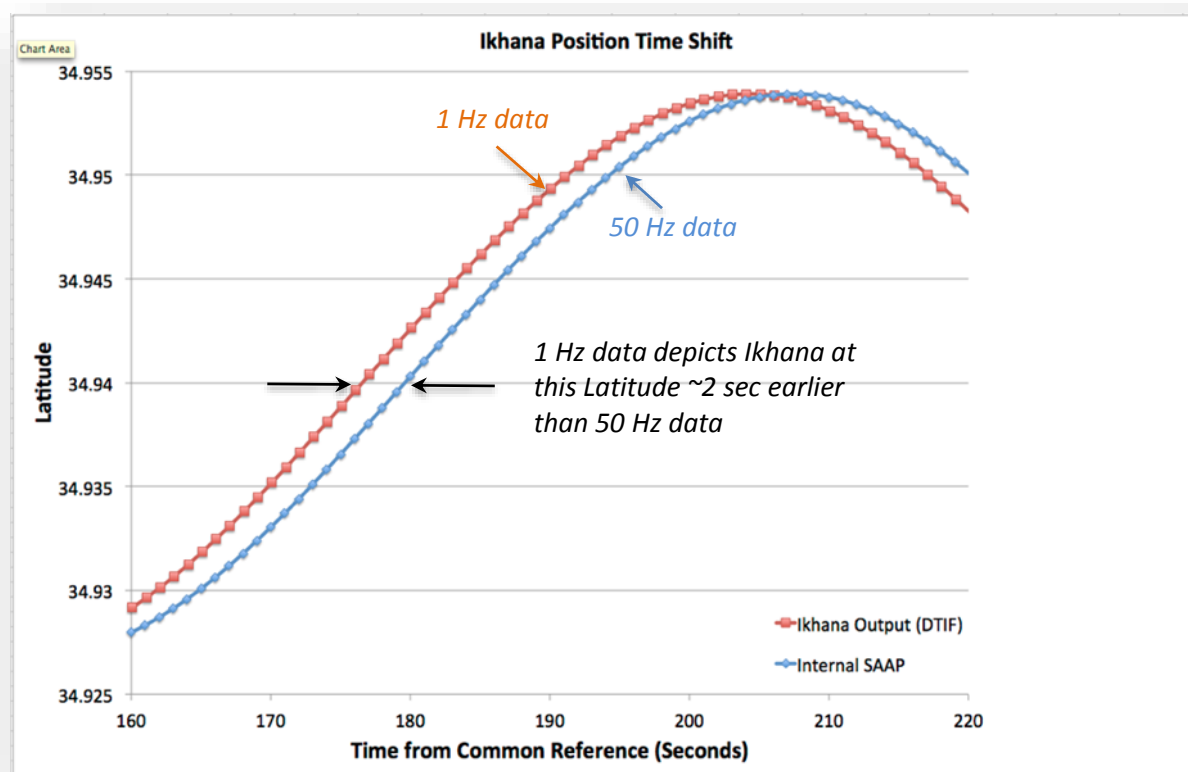


## Backup Charts



# Background Information

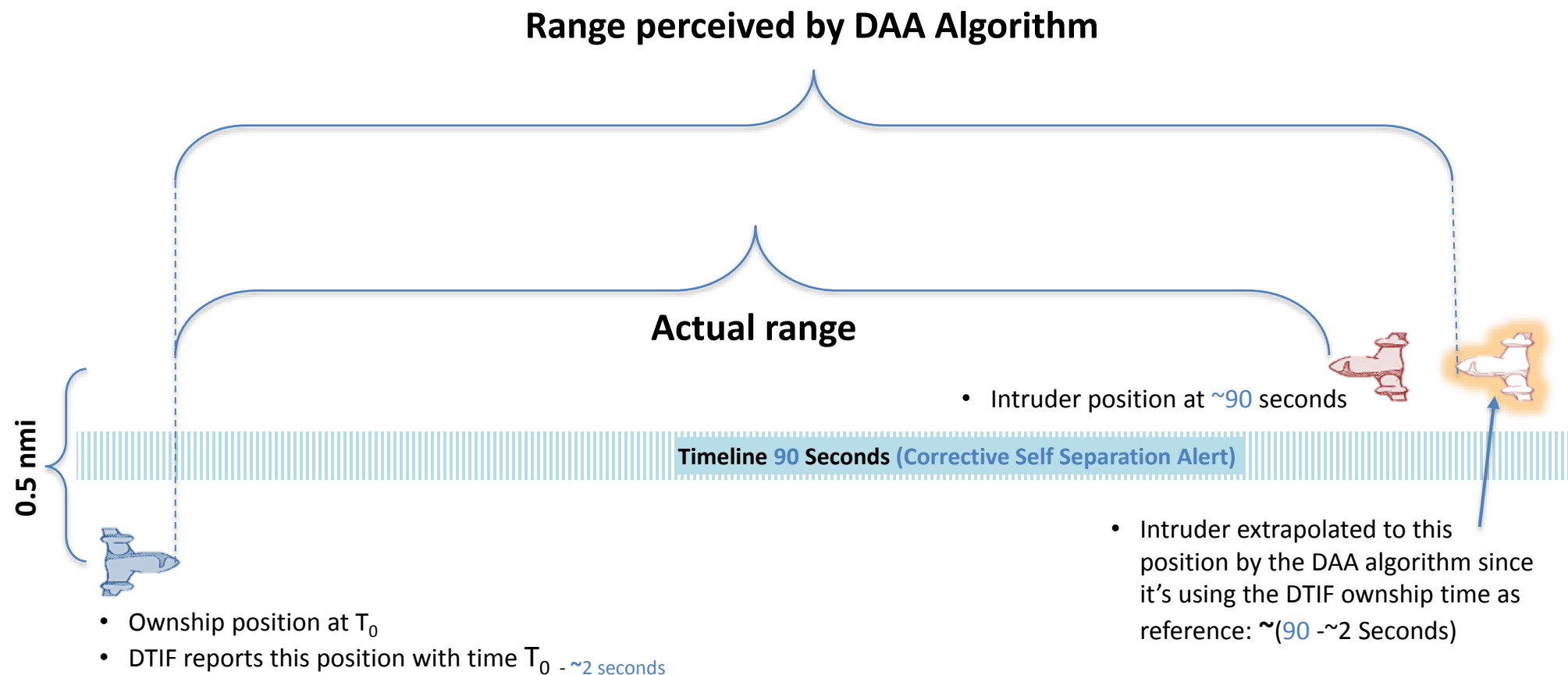
- During the FT3 Data Review, the IT&E co-PE from Ames identified a timing discrepancy in the ownship 1 Hz message containing position data (latitude, longitude) from Ikhana when compared to:
  - 10 Hz & 50 Hz ownship messages on Ikhana
  - Independent GPS data from Ikhana



Graphs from Jim Murphy presentation 'FT3\_data\_analysis\_v7.pptx'

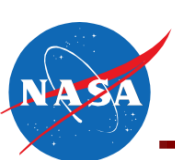


# Representation of Timing Discrepancy

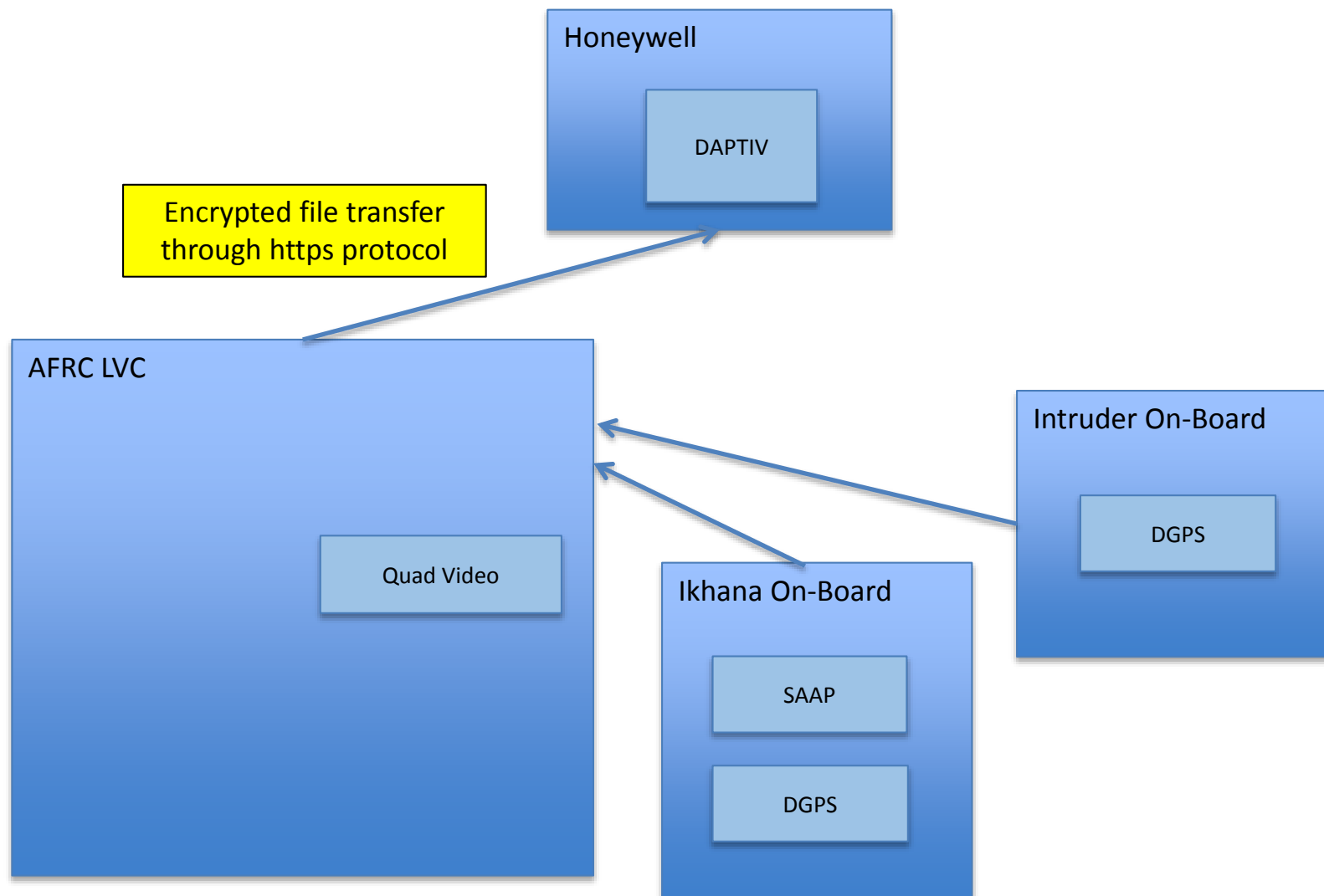








# Data Collection Archiving



Reference: Flight Test Series 4 Data Management Plan, FT4 IT&E DMP-001